

1. Introduction and Decomposition

Ner 20 million people travel through Boston every year. At some point, locals and visitors will need U to stop for gas. Our goal is to model the Energy Information Administration's collection of retail gas prices in Boston for all grades from January 2010 to December 2019 and predict future gas prices over the next five years until 2025. Modeling and forecasting data over time requires methods beyond regression. For example, residual assumptions such as constant variance and Normality generally do not hold for time-dependent data. A linear relationship between the predictor and response rarely exists. Furthermore, the most significant issue is that autocorrelation between observations refutes the premise of mutual independence. We can employ time series analysis (a stochastic process with an indexed collection of random variables that randomly evolves) to perform thorough statistical inference. Our first step starts with plotting the data over time to look for seasonality, the periods of predictable cyclic patterns.

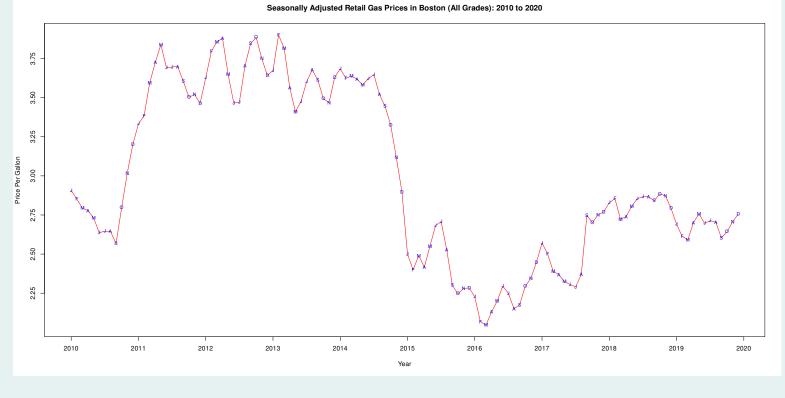


Figure 1: Seasonally Adjusted Data

• The seasonally adjusted retail gas prices in Boston range from \$2.05 to \$3.9 per gallon.

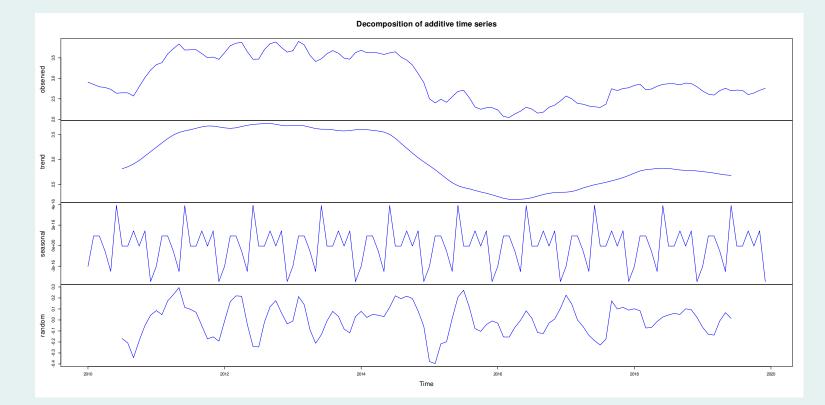


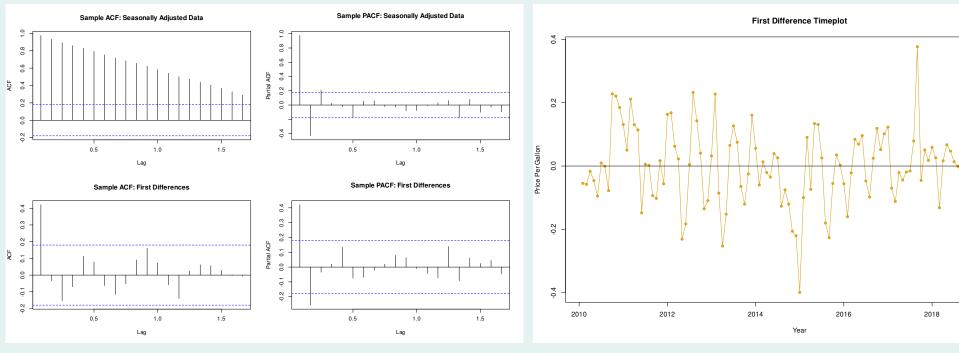
Figure 2: Additive Decomposition of Time Series

• This additive decomposition breaks down our series into four components used for abstraction.

2. Autocorrelation and Differencing

The Difference Process

- Differencing begins by subtracting the previous observation from the current observation.
- A process made stationary by differencing is an integrated time series [1].
- ACF: autocorrelation function \rightarrow measures the linear relationship between current and previous observations with linear dependency
- PACF: partial autocorrelation function \rightarrow measures the linear relationship between current and previous observations with the linear dependency removed
- MA(q): a moving average process of order q with parameter θ , where the current value relies on previous residuals
- AR(p): an autoregressive process of order p with parameter ϕ , where the current value relies on previous observations



- Figure 3: Sample Correlograms Figure 4: First Difference Process • Before Differencing: sample ACF decays slowly, suggesting first differences should be taken, and the sample PACF cuts off after lag k = 3 (vertical bars fall within blue dashed lines)
- After Differencing: sample ACF cuts off after lag k = 1, and the sample PACF cuts off after lag k = 2

		AR(p)	IMA(q)			
ACF	-	Tails off	Cuts off after lag q			
PAC	F	Cuts off after lag p	Tails off			
Table 1: ACF and PACF Behavior						

Time Series Analysis of Retail Gas Prices in Boston

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3. Stationarity Testing and Invertibility

Stationarity Testing

- Aside from the sample ACF and PACF correlograms in the previous section, we can use more formal tests for stationarity (a condition where the properties of the data are constant throughout time).
- A stationary process is a series that exhibits zero trends, no seasonality, and has constant variance.
- KPSS: determines if the trend of a series or the level (observed) values are stationary
- ADF: ascertains if a unit root is present in a series

Test	Test Statistic p-value		Conclusion	
ADF	-2.1538	0.5127	little to no evidence of stationarity	
KPSS (Level)	0.4916	0.0436	strong evidence of nonstationarity	
KPSS (Trend)	0.1192	0.0996	some evidence of nonstationarity	

Table 2: Stationarity Test Results Before Differencing

Test	Test Statistic	p-value	Conclusion
ADF	-2.5536	0.3467	little to no evidence of stationarity
KPSS (Level)	0.1242	> 0.1	little to no evidence of nonstationarity
KPSS (Trend)	0.1165	> 0.1	little to no evidence of nonstationarity

 Table 3: Stationarity Test Results After Differencing

- In the table before differencing, all three tests result in evidence against the stationarity of the gas price data.
- However, after differencing, both KPSS tests suggest that our integrated series is stationary.
- From the ADF test, a complex unit root exists due to the sinusoidal pattern seen after differencing in the previous section.

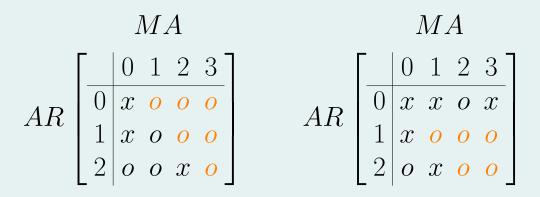
Invertibility Requirements

- A series is invertible if the residuals represent a linear function of current and past observations.
- Invertibility allows us to calculate the model's parameters [3].
- For an MA(q) process to be invertible, we need the roots of the MA characteristic polynomial to all exceed one in absolute value (or modulus, for this series).
- If $|\theta| > 1 \iff$ distant observations have a more significant effect on current observations.
- If $|\theta| = 1 \iff$ all observations have the same influence as the current observations.
- If $|\theta| < 1 \iff$ recent observations have a more significant effect on current observations.

4. Order Specification and Parameter Estimation

The Extended Autocorrelation Function

- Now that we have enough evidence that our series is stationary, we can specify the order and estimate the parameters of our model.
- Since the sample ACF and PACF correlograms show evidence that an AR or MA model is appropriate, we can use the EACF to determine the order of a mixed ARMA process that models the gas price data within our ten-year timeframe.
- Our EACF on the left forms a wedge with its tip at the top left point (0,1), suggesting an MA(1) model.
- The EACF on the right is an example that would suggest an ARMA(1,1) process.



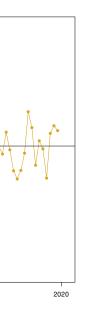
Akaike and Bayesian Information Criterion

- Given the output of the EACF and by the principle of parsimony, we will use an MA(1) process to model the gas prices.
- The auto.arima function in R selects the order of the series via the Hyndman-Khandakar algorithm.

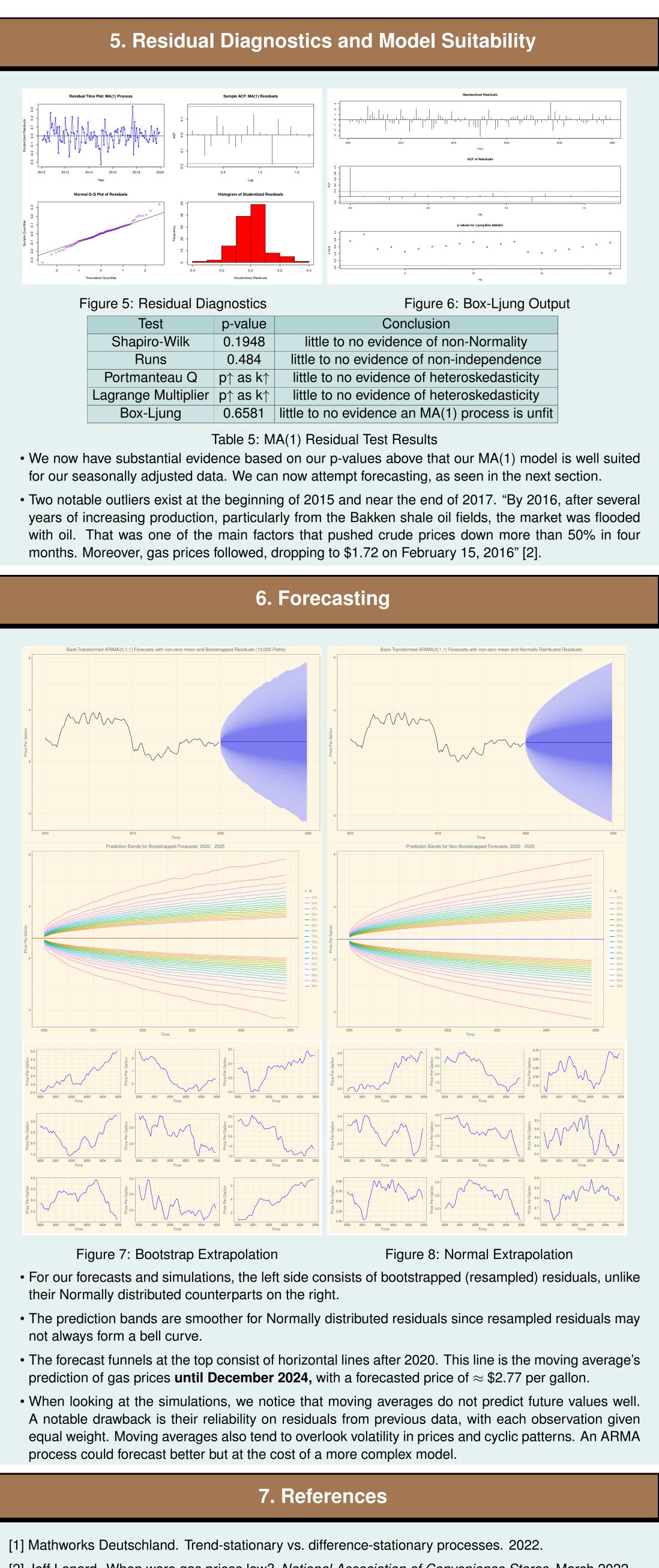
Criterion	Seasonally Adjusted	First Differences
AIC	$ARIMA(0,1,1) \equiv IMA(1,1)$	MA(1)
BIC	$ARIMA(0,1,1) \equiv IMA(1,1)$	MA(1)

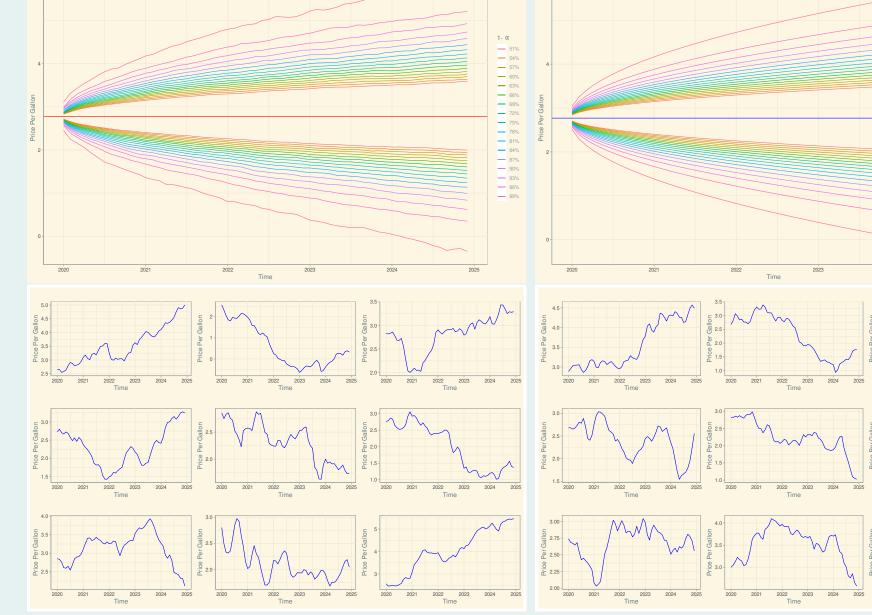
 Table 4: Order Specification Before & After Differencing

- Both model selection methods agree that a first-order integrated moving average fits our data.
- The integrated moving average before differencing is equivalent to the moving average after differencing.
- Maximum Likelihood Estimation (MLE) maximizes the log-likelihood function of the ARIMA model to estimate its parameters.
- We will use the MLE from R to make forecasts.









[2] Jeff Lenard. When were gas prices low? National Association of Convenience Stores, March 2022. [3] PSU. 2.1: Moving average models. *Eberly College of Science: Statistics Online Courses*, 2022.